## Homework 2, due 11-3

In this homework we consider the Lorentz group. The defining representation is four dimensional. The Lorentz group is the set of real matrices  $\Lambda$  that leave the Minkowski space metric invariant

$$\Lambda^T \eta \Lambda = \eta, \qquad \eta = \operatorname{diag}(1, -1, -1, -1), \qquad \operatorname{det}(\Lambda) = 1.$$

With this definition the Lorentz group preserves the inner product of 4-vectors. This means that  $v_{\mu}w^{\mu} = \eta_{\nu\mu}v^{\nu}v^{\mu} = v^{T}\eta w$  is invariant under  $v \to \Lambda v$ ,  $w \to \Lambda w$ .

1. If we write  $\Lambda = \exp(i\alpha_a X_a)$  show that the generators  $X_a$  must satisfy

$$X_a^T \eta + \eta X_a = 0.$$

Determine from this condition and the reality of  $\Lambda$  the number of generators.

2. Show that the six matrices

$$(J_i)_{\mu\nu} = -i\epsilon_{0i\mu\nu}, \qquad (K_i)_{\mu\nu} = -i(\delta_{\mu 0}\delta_{\nu i} - \delta_{\mu i}\delta_{\nu 0}),$$

with i=1,2,3 and  $\mu,\nu=1,\ldots,4$  form a complete basis of the generators  $X_a$ . Here,  $\epsilon_{\mu\nu\alpha\beta}$  is the completely anti-symmetric four index tensor with  $\epsilon_{0123}=+1$ . The  $J_i$  and  $K_i$  are called rotations and boosts, respectively. Are  $J_i,K_i$  hermitean?

- 3. Compute the commutators  $[J_i, J_j]$ ,  $[K_i, K_j]$ ,  $[J_i, K_j]$ .
- 4. Define  $A_i = (J_i + iK_i)/2$  and  $B_i = (J_i iK_i)/2$ . Compute  $[A_i, A_j]$ ,  $[B_i, B_j]$ ,  $[A_i, B_j]$ . Your result shows that the algebra of the Lorentz group is isomorphic to that of  $SU(2) \times SU(2)$ . This implies that representations of the Lorentz group are labeled by pairs of half-integers  $(j_A, j_B)$ .
- 5. Using

$$\alpha_a X_a = \theta_i J_i + \omega_i K_i = (\theta_i - i\omega_i) A_i + (\theta_i - i\omega_i) B_i$$

you can find the explicit form of a Lorentz transformations in the  $(j_A, j_B)$  representation. As an example, consider a two-spinor  $\psi = (\alpha, \beta)^T$  in the (1/2, 0) representation. How does  $\psi$  transform under rotations around the z-axis by an angle  $\theta_3$  or boosts along the z-axis by a boost parameter  $\omega_3$ ?